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/*
*****
* LCD interface example
* Uses routines from delay.c
* This code will interface to a standard LCD controller
* like the Hitachi HD44780. It uses it in 4 bit mode, with
* the hardware connected as follows (the standard 14 pin
* LCD connector is used):
*
* PORTB bits 0-3 are connected to the LCD data bits 4-7 (high nibble)
* PORTA bit 2 is connected to the LCD RS input (register select)
* PORTA bit 3 is connected to the LCD EN bit (enable)
*
* To use these routines, set up the port I/O (TRISA, TRISB) then
* call lcd_init(), then other routines as required.
*
* R/W not used ! Also remember if using port A to set PORTA to digital
***** */

#include <pic.h> // PORTA
#include "lcd.h" // constants
#include "delay.h" // DelayUs, DelayMs
#include "bluebird.h" // BYTE

static bit LCD_RS @ ((unsigned)&PORTA*8+2); // Register select
static bit LCD_EN @ ((unsigned)&PORTA*8+3); // Enable
#define LCD_STROBE ((LCD_EN = 1), (LCD_EN=0)) // Falling edge latches data

/*
*****
* write a byte to the LCD in 4 bit mode
***** */
void lcd_write(unsigned char c)
{
    PORTB = (PORTB & 0xF0) | (c >> 4);
    LCD_STROBE;
    PORTB = (PORTB & 0xF0) | (c & 0x0F);
    LCD_STROBE;
    DelayUs(40);
}

/*
*****
* Clear and home the LCD
***** */
void lcd_clear(void)
{
    LCD_RS = 0;
    lcd_write(0x1);
    DelayMs(2);
}

/*
*****
* write a string of chars to the LCD
***** */
void lcd_puts(const char * s)
{
    LCD_RS = 1; // write characters
    while(*s)
        lcd_write(*s++);
}

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/*****
 * write one character to the LCD
 *****/
void lcd_putchar(char c)
{
    LCD_RS = 1; // write characters
    PORTB = (PORTB & 0xF0) | (c >> 4);
    LCD_STROBE;
    PORTB = (PORTB & 0xF0) | (c & 0x0F);
    LCD_STROBE;
    DelayUs(40);
}

/*****
 * Go to the specified XY position
 * posX = 0 is most left,
 * posY = 0 is first line, posY = 1 is second line
 * datasheet: 3.1.8 "Set DD RAM Address"
 * H.Koch nov.17 2002
 *****/
void lcd_gotoXY(BYTE posX, BYTE posY)
{
    BYTE position;

    if (posX > 39) // max. 40 characters
        posX = 0;
    if (posY > 3) // max. 3 lines
        posY = 0;

    LCD_RS = 0; // write control bytes
    switch(posY)
    {
        case 0: position = (posX + 0x80); // MSB added
according to datasheet
                break;
        case 1: position = (posX + 0x80 + 0x40); // MSB added 0x40 ~
line2
                break;
        default : position = (posX + 0x80);
                break;
    }
    lcd_write(position);
}

/*****
 * Display Control
 *****/
void lcd_displayControl(BYTE displaycontrolvar)
{
    LCD_RS = 0; // write control bytes
    lcd_write((displaycontrolvar & 0x07) | 0x08); // set display control
}

/*****
 * Entry Mode
 *****/
void lcd_entryMode(BYTE entrymodevar)
{
    LCD_RS = 0; // write control bytes
    lcd_write((entrymodevar & 0x03) | 0x04); // set display control
}

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}

/* *****
 * Function Set
 *****/
void lcd_functionSet(BYTE functionsetvar)
{
    LCD_RS = 0;           // write control bytes
    lcd_write((functionsetvar & 0x1C) | 0x20); // set display control
}

/* *****
 * Cursor or Display Shift
 *****/
void lcd_cursorDisplayShift(BYTE cursordisplayshiftvar)
{
    LCD_RS = 0;           // write control bytes
    lcd_write((cursordisplayshiftvar & 0x0C) | 0x10); // set display
control
}

/* *****
 * initialise the LCD - put into 4 bit mode
 *****/
void lcd_init(void)
{
    DelayMs(15);           // power on delay
    PORTB = 0x3;          // attention!
    LCD_STROBE;
    DelayMs(5);
    LCD_STROBE;
    DelayUs(100);
    LCD_STROBE;
    DelayMs(5);
    PORTB = 0x2;          // set 4 bit mode
    LCD_STROBE;
    DelayUs(40);
    lcd_functionSet(LCD_4_BITS | LCD_2_LINES | LCD_5x7_DOTS);
    lcd_entryMode(LCD_SHIFT_OFF | LCD_INCREMENT);
    lcd_cursorDisplayShift(LCD_CURSOR_MOVE | LCD_SHIFT_RIGHT);
    lcd_displayControl(LCD_DISPLAY_ON | LCD_CURSOR_OFF | LCD_BLINK_OFF);
// display on
}
```